

Lecture

Pressure

The goal is to introduce the notion of pressure as a thermodynamic variable. Remember that the variation in terms of the thermodynamic variables of the internal energy was (in the grand canonical distribution)

$$du = \underbrace{T ds}_{\downarrow} + \underbrace{\mu d\langle N \rangle}_{\downarrow} + \underbrace{\sum_{\text{states}} P_j dE_j}_{\downarrow}$$

these two terms are already expressed in terms of averaged values; that is they are in a thermodynamic form

This term still exhibit the probabilities P_j . We want to write this term in terms of some (still to find!) average values.

To guide our way towards the final resolution of $\sum_{\text{states}} P_j d\bar{\epsilon}_j$, let's remember two types of energy spectra:

(1) For a free particle in 3-dimensions

$$E_j = \frac{h^2}{8mL^2} (n_1^2 + n_2^2 + n_3^2)$$

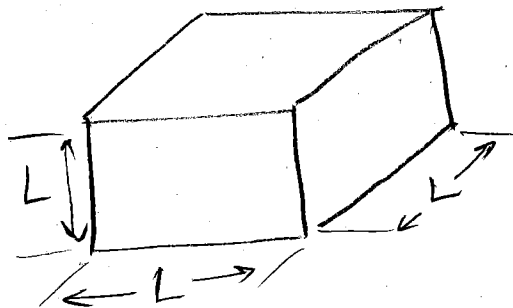
with $j = (n_1, n_2, n_3)$

and $n_1 = 1, 2, 3, \dots$

$n_2 = 1, 2, 3, \dots$

$n_3 = 1, 2, 3, \dots$

Here m is the mass of the particle which is in a 3-dimensional box of side L



Because the volume of the box is

$$V = L^3$$

we can express the energy in terms of the volume V

$$E_j = \frac{h^2}{8mV^{2/3}} (n_1^2 + n_2^2 + n_3^2)$$

Conclusion: E_j is a function of the volume

$$E_j(V)$$

the volume is a thermodynamic parameter

(2) For a paramagnet, the energy was

$$E_j = - (j_1 + j_2 + \dots + j_N) B$$

with $j = (j_1, j_2, \dots, j_N)$

$$j_k = \pm \mu, \quad k = 1, \dots, N$$

Conclusion

field B

E_j is a function of the magnetic

$$E_j(B)$$

and B is a thermodynamic parameter

For other systems, the energy E_j will depend on both the volume V and the magnetic field B

$$E_j(V, B).$$

We can extend the list of thermodynamic parameters to include the electric field, for example.

$$E_j(V, B, \underbrace{x_1, x_2, \dots, x_M}_{\text{other thermodynamic parameters}})$$

other thermodynamic parameters.

Now we can go to $\sum_j P_j dE_j$ and put it in a form of an average value

$$\sum_j P_j dE_j = \sum_j P_j \left(\frac{\partial E_j}{\partial V} dV + \frac{\partial E_j}{\partial B} dB + \frac{\partial E_j}{\partial x_1} dx_1 + \dots + \frac{\partial E_j}{\partial x_M} dx_M \right) =$$

$$= \left\langle \frac{\partial E_j}{\partial V} \right\rangle_{GC} dV + \left\langle \frac{\partial E_j}{\partial B} \right\rangle_{GC} dB + \left\langle \frac{\partial E_j}{\partial x_1} \right\rangle_{GC} dx_1 + \dots +$$

$$+ \left\langle \frac{\partial E_j}{\partial x_M} \right\rangle_{GC} dx_M$$

grand canonical probability distribution

the term $\left\langle \frac{\partial E_j}{\partial B} \right\rangle_{GC}$ has a physical meaning:

$$It\ is\ \left\langle \frac{\partial}{\partial B} \left[- (j_1 + \dots + j_N) B \right] \right\rangle_{GC} =$$

$$= - \left\langle j_1 + \dots + j_N \right\rangle_{GC} = - \left\langle M \right\rangle_{GC}$$

↑
average magnetization
in the grand canonical distribution

Likewise, the term $\left\langle \frac{\partial E_j}{\partial V} \right\rangle_{GC}$ has a physical meaning (a very important one!). To find its meaning, notice its contribution to the variation of the internal energy U

$$dU = T ds + \mu d\langle N \rangle_{GC} + \boxed{\left\langle \frac{\partial E_j}{\partial V} \right\rangle_{GC} dV} - \langle M \rangle_{GC} dB +$$

$$+ \left\langle \frac{\partial E_j}{\partial x_1} \right\rangle_{GC} dx_1 + \dots + \left\langle \frac{\partial E_j}{\partial x_r} \right\rangle_{GC} dx_r$$

When we change the volume (dV) the energy will change with

$$\left\langle \frac{\partial E_j}{\partial V} \right\rangle_{GC} dV$$

From practice we know that a change in volume is related to the pressure applied to the system. Also we know that if $dV < 0$ (we reduce the volume) the energy dU increases, $dU > 0$. We will identify the thermodynamic pressure p with

$$p = - \left\langle \frac{\partial E_j}{\partial V} \right\rangle_{GC}$$

Thus

$$dU = T ds + \mu d\langle N \rangle - p dV - \langle M \rangle_{GC} dB +$$

$$+ \left\langle \frac{\partial E_j}{\partial x_1} \right\rangle dx_1 + \dots + \left\langle \frac{\partial E_j}{\partial x_r} \right\rangle dx_r$$

these terms will acquire a physical meaning when you give a physical meaning for x_1, \dots, x_r (which depends on your specific problem)

Important property for pressure
and grand canonical partition
function

$$pV = kT \log \Delta \quad (*)$$

We will show that (*) is correct in
what follows. Before that, notice the
value of this relation. Once you computed
the grand canonical partition function Δ
and thus retain only the thermodynamic
variables, that is

$\Delta =$ function of T, μ and V
You will have a relation between the
thermodynamic variables

(P) V , T , μ
pressure , Volume , temperature , chemical potential

You can use such a relation to find
the pressure if you know V, T, μ ; or to
find μ if you know P, V and T . Such a
relation is called an equation of state
in thermodynamics (of course here "state"
means a thermodynamic state P, V, T, μ , and
not a microstate).

Now lets show that $pV = kT \log \Delta$.

From the definition of $\Delta(T, \mu, V)$

$$\Delta(T, \mu, V) = \sum_{N=0}^{\infty} e^{\beta \mu N} \sum_{j_N} e^{-\beta E_{j_N}}$$

and from the fact that the energy E_{j_N} depends on the volume V , it follows

that

$$\frac{\partial \Delta}{\partial V} = \sum_{N=0}^{\infty} e^{\beta \mu N} \sum_{j_N} -\beta \frac{\partial E_{j_N}}{\partial V} e^{-\beta E_{j_N}}$$

Notice that the independent variables in Δ are T, μ and V . That is, μ and T are independent of the volume V so the derivative will act only on $E_{j_N}(V)$.

To get an average value, we divide by

Δ

$$\frac{1}{\Delta} \frac{\partial \Delta}{\partial V} = \sum_{N=0}^{\infty} e^{\beta \mu N} \sum_{j_N} -\beta \frac{\partial E_{j_N}}{\partial V} \frac{e^{-\beta E_{j_N}}}{\Delta} =$$

$$= \beta \sum_{\text{grand states}} - \frac{\partial E_{\text{grand states}}}{\partial V} \underbrace{P_{\text{grand states}}}_{\text{grand canonical probabilities}}$$

So

$$\frac{\partial \log \Lambda}{\partial V} = \beta \left(- \frac{\partial E_{\text{grand states}}}{\partial V} \right)_{GC}$$

pressure

$$\frac{\partial \log \Lambda}{\partial V} = \frac{1}{kT} P$$

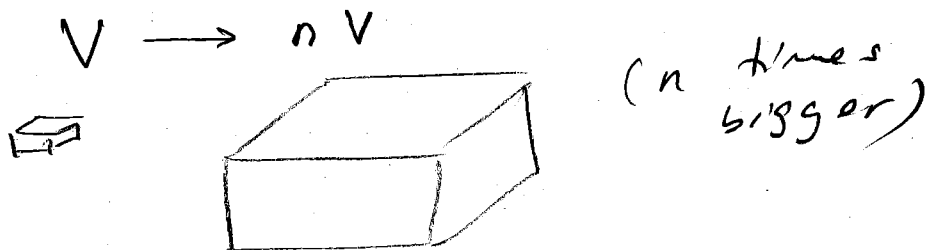
or

$$P = kT \frac{\partial \log \Lambda}{\partial V}$$

This is also a good formula to find the thermodynamic equation of state. However, we can go even further to show that

$$\frac{\partial \log \Lambda}{\partial V} = \frac{\log \Lambda}{V} \quad (**)$$

Before we show this, we will talk about the meaning of (**). It says that the grand partition function scales very simply with the volume, that is, if you increase the volume n times

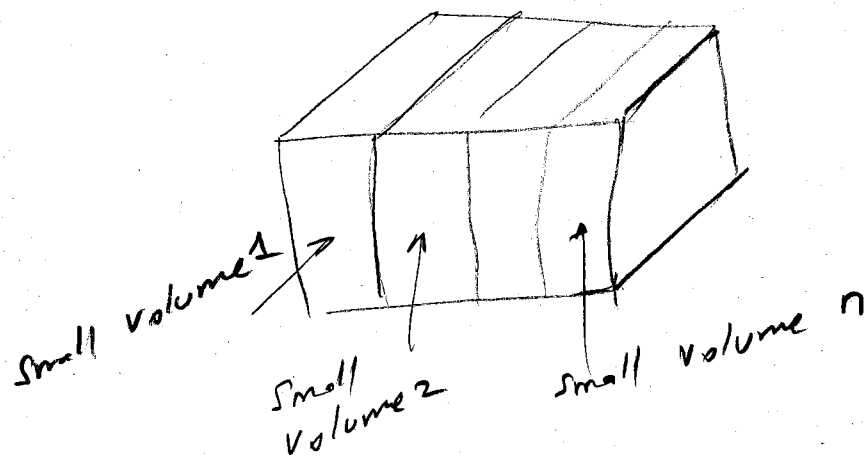


the logarithm of the grand canonical partition function also increases n times

$$\log \Delta(T, \mu, nV) = n \log \Delta(T, \mu, V)$$

In other words

$$\log \Delta(\text{big volume}) = \sum_{\text{subsystems of the big system}} \log \Delta(\text{small volumes})$$



Now $(**)$ comes out of this scaling behavior. Indeed, write

$$\log \Delta(T, \mu, nV) = n \log \Delta(T, \mu, V)$$

In terms of

$$V_{\text{big}} = nV$$

$$V_{\text{small}} = V$$

$$\log \Delta(T, \mu, V_{\text{big}}) = \frac{V_{\text{big}}}{V_{\text{small}}} \log \Delta(T, \mu, V_{\text{small}})$$

Now take $V_{\text{small}} = 1 \text{ m}^3$ (the unit volume)

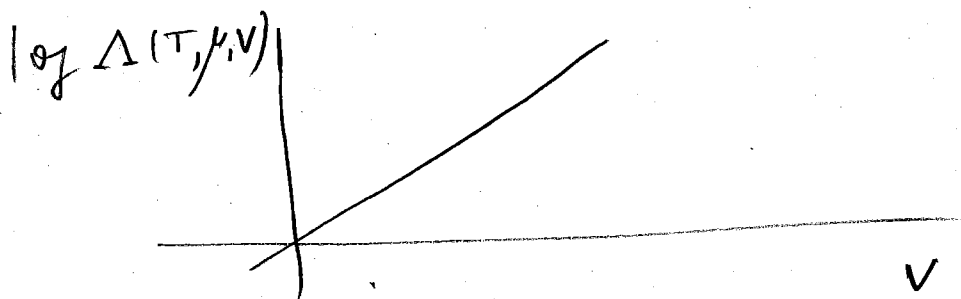
$$\log \Delta(T, \mu, V_{\text{big}}) = V_{\text{big}} \log \Delta(T, \mu, 1)$$

and get rid of the index "big".

For any volume V we have

$$\log \Delta(T, \mu, V) = V \log \Delta(T, \mu, 1)$$

In other words $\log \Delta(T, \mu, V)$ is simply proportional with the volume V



The result is very simple. The V argument of scaling is worth to remember.

Now the relation

$$\frac{\partial \log \Delta(T, \mu, V)}{\partial V} = \frac{\log \Delta(T, \mu, V)}{V}$$

is very easy to prove because of the linearity
 In V ,
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$$\frac{\partial \log \Lambda(T, \mu, V)}{\partial V} = \log \Lambda(T, \mu, 1) = \frac{\log \Lambda(T, \mu, V)}{V}$$

To finish the proof of

$$pV = kT \log \Lambda$$

We need to show that $\log \Lambda$ has the scaling property. The argument for the scaling property is as follows.

Let us divide the volume V into n parts of equal volume $\frac{V}{n}$ by inserting walls which can transmit both heat and particles. The total system is in contact with a heat-particle source with fixed μ and T (of course, because we are in the grand canonical distribution). The macroscopic properties are not affected by the insertion of the walls. One can regard each part as independent, assuming the interaction between the system and the walls, as well as the interactions between the parts, to be weak. Therefore, when N_1, N_2, \dots are distributed in the respective parts, the canonical partition function of the whole system $\Omega(N_1, N_2, \dots, T, V)$ is equal to the product of the canonical partition

function of each part (see also the homework):

$$\mathcal{Z}(N_1, N_2, \dots, T, V) = \mathcal{Z}(N_1, T, \frac{V}{n}) \mathcal{Z}(N_2, T, \frac{V}{n}) \dots$$

Substituting this into the definition of the grand canonical partition function Δ , we have

$$\begin{aligned} \Delta(T, \mu, V) &= \sum_{N=0}^{\infty} e^{\beta \mu N} \sum_{N_1 + N_2 + \dots = N} \mathcal{Z}(N_1, N_2, \dots, T, V) = \\ &= \sum_{N=0}^{\infty} e^{\beta \mu (N_1 + N_2 + \dots)} \sum_{N_1 + N_2 + \dots = N} \mathcal{Z}(N_1, T, \frac{V}{n}) \mathcal{Z}(N_2, T, \frac{V}{n}) \dots = \end{aligned}$$

$$= \left[\sum_{N_1=0}^{\infty} e^{\beta \mu N_1} \mathcal{Z}(N_1, T, \frac{V}{n}) \right] \left[\sum_{N_2=0}^{\infty} e^{\beta \mu N_2} \mathcal{Z}(N_2, T, \frac{V}{n}) \right] \dots$$

$$= \left[\Delta(T, \mu, \frac{V}{n}) \right]^n$$

so

$$\log \Delta(T, \mu, V) = n \log \Delta(T, \mu, \frac{V}{n})$$

If the assumptions of weak interactions that we used in proving the scaling argument are not realized in some system, then we will use

$$p = kT \frac{\partial \log \Lambda}{\partial V} \quad (1)$$

Instead of

$$p = kT \frac{\log \Lambda}{V} \quad (2)$$

Remember that (1) was found without the scaling argument.

More about pressure

The pressure was defined as the grand canonical average value of $-\frac{\partial E_{\text{grand state}}}{\partial V}$

$$p_{GC} = \left\langle -\frac{\partial E_{\text{grand state}}}{\partial V} \right\rangle_{GC} = \sum_{N=0}^{\infty} e^{\beta \mu N} \sum_{j_N} -\frac{\partial E_{j_N}}{\partial V} \frac{e^{-\beta E_{j_N}}}{\Lambda} =$$

$$= \sum_{N=0}^{\infty} e^{\beta\mu N} \frac{1}{\Lambda} \sum_N \sum_{j_N} - \frac{\partial E_{j_N}}{\partial V} \frac{e^{-\beta E_{j_N}}}{\sum_N} =$$

by inserting \sum_N here we try to get towards the canonical distribution

$$= \sum_{N=0}^{\infty} e^{\beta\mu N} \frac{1}{\Lambda} \sum_N \left\langle - \frac{\partial E_{j_N}}{\partial V} \right\rangle_{\text{canonical}, N}$$

So

$$P_{\text{grand canonical}} = \sum_{N=0}^{\infty} e^{\beta\mu N} \frac{\sum_N P_{\text{canonical}, N}}{\Lambda} \quad (3)$$

pressure in the grand canonical distribution

pressure in a canonical distribution, for a system with fixed N particles

We conclude that, when the system does not exchange particles with the exterior (canonical distribution), we need to use $P_{\text{canonical}}$

The pressure in the canonical distribution can be obtained from the canonical partition function $\Omega(T, V, N)$ (notice that we do not have the chemical potential μ as a variable here)

$$\Omega(T, V, N) = \sum_{\text{Canonical states}} e^{-\beta E_{\text{Canonical states}}}$$

So

$$\frac{\partial \Omega}{\partial V} = \sum_{\text{Canonical states}} -\beta \frac{\partial E_{\text{Canonical states}}}{\partial V} e^{-\beta E_{\text{Canonical states}}}$$

Divide by Ω to obtain probabilities on the right side

$$\frac{1}{\Omega} \frac{\partial \Omega}{\partial V} = \beta \sum_{\text{Canonical states}} - \frac{\partial E_{\text{Canonical states}}}{\partial V} \underbrace{\frac{e^{-\beta E_{\text{Canonical states}}}}{\Omega}}_{P_{\text{Canonical state}}}$$

$$\frac{\partial \ln \Omega}{\partial V} = \beta \left\langle - \frac{\partial E_{\text{Canonical states}}}{\partial V} \right\rangle_{\text{Canonical}}$$

$P_{\text{Canonical}}$

or

$$P_{\text{Canonical}} = kT \frac{\partial \ln \Omega}{\partial V} \quad (4)$$

In microcanonical case, the energy is constant

$$E = \text{constant}$$

For example, for the free particle in a box

$$E = \frac{h^2}{8mV^{2/3}} (n_1^2 + n_2^2 + n_3^2)$$

$$n_1 = 1, 2, \dots$$

$$n_2 = 1, 2, \dots$$

$$n_3 = 1, 2, \dots$$

and fixing E we can find $\Omega(E)$, the number of states (n_1, n_2, n_3) such that

$$n_1^2 + n_2^2 + n_3^2 = E \cdot \frac{8mV^{2/3}}{h^2} \quad (5)$$

Because we talk about pressure now, the volume V which was fixed up to now, must be considered a parameter which can be varied. Keeping E fixed, when we vary the volume V , the radius of the sphere (5) will change, so that the number of states (n_1, n_2, n_3) that obeys (5) will depend on volume also:

$$\Omega(E, V)$$

Looking at the microcanonical distribution as an approximation of the canonical one we have

$$\Sigma \cong \Omega(E, V) e^{-\beta E}$$

Now the canonical pressure can be approximated as follows

$$P_{\text{canonical}} = kT \frac{\partial \ln \Sigma}{\partial V} \stackrel{\text{approximation}}{\cong} kT \frac{\partial (\ln \Omega(E, V) - \beta E)}{\partial V} =$$

$$= kT \frac{\partial \ln \Omega(E, V)}{\partial V}$$

This term disappears because $E = \text{constant}$ in microcanonical distribution.

We can thus define

$$P_{\text{microcanonical}} = kT \left(\frac{\partial \ln \Omega(E, V)}{\partial V} \right)_{E, N}$$

KEEP E and N constant